

MTH 237 — PROBLEM SET 08 SOLUTIONS

1. Solve the following equations using the Laplace transform method.

i) $\frac{dy}{dt} - y = e^t, \quad y(0) = 1.$

ii) $\frac{d^2y}{dt^2} + 4\frac{dy}{dt} + 4y = 0, \quad y(0) = 1, \quad \frac{dy}{dt}(0) = 1.$

iii) $\frac{d^2y}{dt^2} - 2\frac{dy}{dt} + 5y = 0, \quad y(0) = 2, \quad \frac{dy}{dt}(0) = 4.$

iv) $\frac{d^3y}{dt^3} - 2\frac{d^2y}{dt^2} + \frac{dy}{dt} = 2e^t + 2t, \quad y(0) = 0, \quad \frac{dy}{dt}(0) = 0, \quad \frac{d^2y}{dt^2}(0) = 0.$

Optional Problem. Also solve the two equations from Problem Set 6 using the Laplace transform:

v) $\frac{d^2y}{dt^2} + \frac{dy}{dt} - 2y = 2t, \quad y(0) = 0, \quad \frac{dy}{dt}(0) = 1.$

vi) $\frac{d^2y}{dt^2} + 16y = t^2 + \sin(4t), \quad y(0) = \frac{127}{128}, \quad \frac{dy}{dt}(0) = \frac{7}{8}.$

These will require more algebraic manipulations to get the expression for $\mathcal{L}[y](s)$ into a form where the inverse transform can be found by inspection.

Solution. i) Taking Laplace transforms of both sides, we get

$$\mathcal{L}[y'](s) - \mathcal{L}[y](s) = \mathcal{L}[e^t](s)$$

or

$$(s\mathcal{L}[y](s) - y(0)) - \mathcal{L}[y](s) = \frac{1}{s-1}.$$

Using the initial condition $y(0) = 1$, and grouping like terms, we get

$$(s-1)\mathcal{L}[y](s) - 1 = \frac{1}{s-1}$$

so that, solving for $\mathcal{L}[y](s)$,

$$\mathcal{L}[y](s) = \frac{1}{s-1} + \frac{1}{(s-1)^2}.$$

By inspection, the inverse Laplace transform is

$$y(t) = e^t + te^t.$$

ii) Taking Laplace transforms of both sides, we get

$$\mathcal{L}[y''](s) + 4\mathcal{L}[y'](s) + 4\mathcal{L}[y](s) = 0$$

or

$$(s^2\mathcal{L}[y](s) - sy(0) - y'(0)) + 4(s\mathcal{L}[y](s) - y(0)) + 4\mathcal{L}[y](s) = 0.$$

Grouping like terms and applying the initial conditions, we get

$$(s^2 + 4s + 4)\mathcal{L}[y](s) - s - 5 = 0,$$

so that

$$\mathcal{L}[y](s) = \frac{s+5}{s^2+4s+4} = \frac{s+5}{(s+2)^2} = \frac{1}{s+2} + \frac{3}{(s+2)^2}.$$

Taking the inverse Laplace transform by inspection, we find

$$y(t) = e^{-2t} + 3te^{-2t}.$$

iii) Taking Laplace transforms of both sides, we get

$$\mathcal{L}[y''](s) - 2\mathcal{L}[y'](s) + 5\mathcal{L}[y](s) = 0,$$

or

$$(s^2\mathcal{L}[y](s) - sy(0) - y'(0)) - 2(s\mathcal{L}[y](s) - y(0)) + 5\mathcal{L}[y](s) = 0.$$

Grouping like terms and applying the initial conditions, we have

$$(s^2 - 2s + 5)\mathcal{L}[y](s) - 2s = 0,$$

so that

$$\mathcal{L}[y](s) = \frac{2s}{s^2 - 2s + 5} = \frac{2s}{(s-1)^2 + 4} = \frac{2(s-1) + 2}{(s-1)^2 + 4} = 2\frac{s-1}{(s-1)^2 + 4} + \frac{2}{(s-1)^2 + 4}.$$

Taking the inverse Laplace transform,

$$y(t) = 2e^t \cos(2t) + e^t \sin(2t).$$

Remark. It is also acceptable to do this problem by breaking up $\frac{1}{s^2-2s+5}$ into *complex* partial fractions, although strictly speaking we have not defined the Laplace transform for complex-valued functions. If one proceeds this way, however, after obtaining complex-valued exponentials in the t -domain, it is necessary to apply Euler's formula to the results to obtain real-valued solutions.

For the sake of illustration, here is how this approach would work for this problem. We have

$$\begin{aligned} \frac{2s}{s^2 - 2s + 5} &= \frac{2s}{(s - (1 + 2i))(s - (1 - 2i))} \\ &= \frac{A}{s - (1 + 2i)} + \frac{B}{s - (1 - 2i)} \\ &= \frac{A(s - (1 - 2i)) + B(s - (1 + 2i))}{s^2 - 2s + 5} \end{aligned}$$

Comparing coefficients of s and 1, we get the system of equations

$$\begin{aligned} A + B &= 2 \\ -A(1 - 2i) - B(1 + 2i) &= 0 \end{aligned}$$

Let's solve it using matrix methods from linear algebra. We have

$$\begin{aligned} \left(\begin{array}{cc|c} 1 & 1 & 2 \\ -1+2i & -1-2i & 0 \end{array} \right) &\xrightarrow{R2 \cdot (-1-2i)} \left(\begin{array}{cc|c} 1 & 1 & 2 \\ 5 & -3+4i & 0 \end{array} \right) \\ &\xrightarrow{R2-5R1} \left(\begin{array}{cc|c} 1 & 1 & 2 \\ 0 & -8+4i & -10 \end{array} \right) \\ &\xrightarrow{R2 \cdot 1/(-8+4i)} \left(\begin{array}{cc|c} 1 & 1 & 2 \\ 0 & 1 & 1+\frac{i}{2} \end{array} \right) \quad \left(\frac{-10}{-8+4i} = \frac{-5}{-4+2i} = \frac{-5(-4-2i)}{(-4+2i)(-4-2i)} = \frac{20+10i}{16+4} = 1+\frac{i}{2} \right) \\ &\xrightarrow{R1-R2} \left(\begin{array}{cc|c} 1 & 0 & 1-\frac{i}{2} \\ 0 & 1 & 1+\frac{i}{2} \end{array} \right). \end{aligned}$$

Therefore, $A = 1 - \frac{i}{2}$ and $B = 1 + \frac{i}{2}$. We have

$$\mathcal{L}[y](s) = \frac{2s}{s^2 - 2s + 5} = \left(1 - \frac{i}{2}\right) \frac{1}{1 - (1+2i)} + \left(1 + \frac{i}{2}\right) \frac{1}{1 - (1-2i)}.$$

Taking on faith that the inverse Laplace transform of $\frac{1}{s-a}$ is e^{at} even when a is complex, we then have

$$\begin{aligned} y(t) &= \left(1 - \frac{i}{2}\right) e^{(1+2i)t} + \left(1 + \frac{i}{2}\right) e^{(1-2i)t} \\ &= (e^{(1+2i)t} + e^{(1-2i)t}) - \frac{i}{2} (e^{(1+2i)t} - e^{(1-2i)t}). \end{aligned}$$

By Euler's formula,

$$\frac{e^{\sigma+i\omega} + e^{\sigma-i\omega}}{2} = e^{\sigma} \cos(\omega) \quad \text{and} \quad \frac{e^{\sigma+i\omega} - e^{\sigma-i\omega}}{2i} = e^{\sigma} \sin(\omega).$$

Therefore, using the fact that $i = -\frac{1}{i}$,

$$y(t) = 2e^t \cos(2t) + e^t \sin(2t).$$

iv) Taking Laplace transforms of both sides, we get

$$\mathcal{L}[y''''](s) - 2\mathcal{L}[y''] + \mathcal{L}[y'] = \frac{2}{s-1} + \frac{2}{s^2}.$$

Since the initial conditions are all equal to zero, the left side is particularly simple:

$$s^3 \mathcal{L}[y](s) - 2s^2 \mathcal{L}[y](s) + s \mathcal{L}[y](s) = s(s^2 - 2s + 1) \mathcal{L}[y](s) = s(s-1)^2 \mathcal{L}[y](s) = \frac{2}{s-1} + \frac{2}{s^2}.$$

Therefore,

$$\mathcal{L}[y](s) = \frac{2}{s(s-1)^3} + \frac{2}{s^3(s-1)^2} = \frac{2s^2 + 2(s-1)}{s^3(s-1)^3} = \frac{2s^2 + 2s - 2}{s^3(s-1)^3}.$$

We find the partial fraction decomposition of the last term —

$$\begin{aligned} \frac{2s^2 + 2s - 2}{s^3(s-1)^3} &= \frac{A}{s} + \frac{B}{s^2} + \frac{C}{s^3} + \frac{D}{s-1} + \frac{E}{(s-1)^2} + \frac{F}{(s-1)^3} \\ &= \frac{As^2(s-1)^3 + Bs(s-1)^3 + C(s-1)^3 + Ds^3(s-1)^2 + Ds^3(s-1) + Es^3}{s^3(s-1)^3} \\ &= \frac{A(s^5 - 3s^4 + 3s^3 - s^2) + B(s^4 - 3s^3 + 3s^2 - s) + C(s^3 - 3s^2 + 3s - 1) + D(s^5 - 2s^4 + s^3) + E(s^4 - s^3) + Fs^3}{s^3(s-1)^3} \end{aligned}$$

We get the system of linear equations

$$\begin{aligned}
 A + D &= 0 \\
 -3A + B - 2D + E &= 0 \\
 3A - 3B + C + D - E + F &= 0 \\
 -A + 3B - 3C &= 2 \\
 -B + 3C &= 2 \\
 -C &= -2
 \end{aligned}$$

From the last equation, $C = 2$. From the fifth equation, then, $B = 4$. From the fourth equation, $A = 4$. From the first equation, $A = -D$, so that $D = -4$. Then, from the second equation, $E = 0$. Finally, from the third equation, $F = 2$.

Alternatively, bringing the coefficient matrix to ref,

$$\begin{aligned}
 &\left(\begin{array}{cccccc|c} 1 & 0 & 0 & 1 & 0 & 0 & 0 \\ -3 & 1 & 0 & -2 & 1 & 0 & 0 \\ 3 & -3 & 1 & 1 & -1 & 1 & 0 \\ -1 & 3 & -3 & 0 & 0 & 0 & 2 \\ 0 & -1 & 3 & 0 & 0 & 0 & 2 \\ 0 & 0 & -1 & 0 & 0 & 0 & -2 \end{array} \right) \xrightarrow{R_2+3R_1, R_3-3R_1, R_4+R_1} \left(\begin{array}{cccccc|c} 1 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & -3 & 1 & -2 & -1 & 1 & 0 \\ 0 & 3 & -3 & 1 & 0 & 0 & 2 \\ 0 & -1 & 3 & 0 & 0 & 0 & 2 \\ 0 & 0 & -1 & 0 & 0 & 0 & -2 \end{array} \right) \\
 &\xrightarrow{R_3+3R_2, R_4-3R_2, R_5+R_2} \left(\begin{array}{cccccc|c} 1 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 2 & 1 & 0 \\ 0 & 0 & -3 & -2 & -3 & 0 & 2 \\ 0 & 0 & 3 & 1 & 1 & 0 & 2 \\ 0 & 0 & -1 & 0 & 0 & 0 & -2 \end{array} \right) \\
 &\xrightarrow{R_4+3R_3, R_6-3R_3, R_6+R_3} \left(\begin{array}{cccccc|c} 1 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 2 & 1 & 0 \\ 0 & 0 & 0 & 1 & 3 & 3 & 2 \\ 0 & 0 & 0 & -2 & -5 & -3 & 2 \\ 0 & 0 & 0 & 1 & 2 & 1 & -2 \end{array} \right) \\
 &\xrightarrow{R_5+2R_4, R_6-R_4} \left(\begin{array}{cccccc|c} 1 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 2 & 1 & 0 \\ 0 & 0 & 0 & 1 & 3 & 3 & 2 \\ 0 & 0 & 0 & 0 & 1 & 3 & 6 \\ 0 & 0 & 0 & 0 & -1 & -2 & -4 \end{array} \right) \\
 &\xrightarrow{R_6+R_5} \left(\begin{array}{cccccc|c} 1 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 2 & 1 & 0 \\ 0 & 0 & 0 & 1 & 3 & 3 & 2 \\ 0 & 0 & 0 & 0 & 1 & 3 & 6 \\ 0 & 0 & 0 & 0 & 0 & 1 & 2 \end{array} \right)
 \end{aligned}$$

$$\begin{array}{l}
\begin{array}{c} \xrightarrow{R3-R6, R4-3R6, R5-3R6} \\ \\ \\ \\ \\ \\ \end{array} \\
\begin{array}{c} \xrightarrow{R2-R5, R3-2R5, R4-3R5} \\ \\ \\ \\ \\ \\ \end{array} \\
\begin{array}{c} \xrightarrow{R1-R4, R2-R4, R3-R4} \end{array}
\end{array}
\left(\begin{array}{cccccc|c}
1 & 0 & 0 & 1 & 0 & 0 & 0 \\
0 & 1 & 0 & 1 & 1 & 0 & 0 \\
0 & 0 & 1 & 1 & 2 & 0 & -2 \\
0 & 0 & 0 & 1 & 3 & 0 & -4 \\
0 & 0 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 & 2 \\
\hline
1 & 0 & 0 & 1 & 0 & 0 & 0 \\
0 & 1 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 1 & 1 & 0 & 0 & -2 \\
0 & 0 & 0 & 1 & 0 & 0 & -4 \\
0 & 0 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 & 2 \\
\hline
1 & 0 & 0 & 0 & 0 & 0 & 4 \\
0 & 1 & 0 & 0 & 0 & 0 & 4 \\
0 & 0 & 1 & 0 & 0 & 0 & 2 \\
0 & 0 & 0 & 1 & 0 & 0 & -4 \\
0 & 0 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 & 2
\end{array} \right).$$

Therefore,

$$\frac{2s^2 + 2s - 2}{s^3(s-1)^3} = \frac{4}{s} + \frac{4}{s^2} + \frac{2}{s^3} - \frac{4}{s-1} + \frac{2}{(s-1)^3}.$$

Taking the inverse Laplace transform,

$$y(t) = 4 + 4t + t^2 - 4e^t + t^2e^t.$$

v) Taking Laplace transforms of both sides,

$$\mathcal{L}[y''] + \mathcal{L}[y'] - 2\mathcal{L}[y] = \frac{2}{s^2},$$

or

$$(s^2\mathcal{L}[y](s) - sy(0) - y'(0)) + (s\mathcal{L}[y](s) - y(0)) - 2\mathcal{L}[y](s) = \frac{2}{s^2}.$$

Applying the initial conditions $y(0) = 0$, $y'(0) = 1$,

$$(s^2 + s - 2)\mathcal{L}[y](s) - 1 = \frac{2}{s^2},$$

so that

$$\mathcal{L}[y](s) = \frac{1}{s^2 + s - 2} + \frac{2}{s^2(s^2 + s - 2)} = \frac{1}{(s-1)(s+2)} + \frac{2}{s^2(s-1)(s+2)} = \frac{s^2 + 2}{s^2(s-1)(s+2)}.$$

We find the partial fraction decomposition of the last term —

$$\begin{aligned}
\frac{s^2 + 2}{s^2(s-1)(s+2)} &= \frac{A}{s} + \frac{B}{s^2} + \frac{C}{s-1} + \frac{D}{s+2} \\
&= \frac{As(s^2 + s - 2) + B(s^2 + s - 2) + Cs^2(s+2) + Ds^2(s-1)}{s^2(s-1)(s+2)} \\
&= \frac{A(s^3 + s^2 - 2s) + B(s^2 + s - 2) + C(s^3 + 2s^2) + D(s^3 - s^2)}{s^2(s-1)(s+2)}
\end{aligned}$$

We get the system of linear equations

$$\begin{aligned} A + C + D &= 0 \\ A + B + 2C - D &= 1 \\ -2A + B &= 0 \\ -2B &= 2 \end{aligned}$$

From the last equation, $B = -1$. Then, from the third, $A = -1/2$. Adding the first two, $2A + B + 3C = 1$, so $C = 1$. Finally, from the first, $D = -1/2$.

$$\frac{s^2 + 2}{s^2(s-1)(s+2)} = -\frac{1}{2} \frac{1}{s} - \frac{1}{s^2} + \frac{1}{s-1} - \frac{1}{2} \frac{1}{s+2}.$$

Taking the inverse Laplace transform,

$$y(t) = -\frac{1}{2} - t + e^t - \frac{1}{2}e^{-2t}.$$

vi) Taking Laplace transforms of both sides,

$$\mathcal{L}[y''](s) + 16\mathcal{L}[y](s) = \frac{2}{s^3} + \frac{4}{s^2 + 16},$$

or

$$(s^2 + 16)\mathcal{L}[y](s) - \frac{127s}{128} - \frac{7}{8} = \frac{2}{s^3} + \frac{4}{s^2 + 16}.$$

So

$$\mathcal{L}[y](s) = \frac{7}{8} \frac{1}{s^2 + 16} + \frac{127}{128} \frac{s}{s^2 + 16} + \frac{2}{s^3(s^2 + 16)} + \frac{4}{(s^2 + 16)^2}.$$

We find the partial fraction decomposition of the third term —

$$\begin{aligned} \frac{2}{s^3(s^2 + 16)} &= \frac{A}{s} + \frac{B}{s^2} + \frac{C}{s^3} + \frac{Ds + E}{s^2 + 16} \\ &= \frac{As^2(s^2 + 16) + Bs(s^2 + 16) + C(s^2 + 16) + Ds^4 + Es^3}{s^3(s^2 + 16)} \\ &= \frac{A(s^4 + 16s^2) + B(s^3 + 16s) + C(s^2 + 16) + Ds^4 + Es^3}{s^3(s^2 + 16)}. \end{aligned}$$

The solution is $A = -1/128$, $B = 0$, $C = 1/8$, $D = 1/128$, $E = 0$. We get (after rearranging slightly)

$$\mathcal{L}[y](s) = -\frac{1}{128} \frac{1}{s} + \frac{1}{8} \frac{1}{s^3} + \frac{s}{s^2 + 16} + \frac{7}{8} \frac{1}{s^2 + 16} + \frac{4}{(s^2 + 16)^2}.$$

Because of the term $\frac{1}{(s^2+16)^2}$, we recognize some transforms of functions of type $t \cos$ and $t \sin$. We have (from Problem 2)

$$\mathcal{L}[t \cos(\omega t)](s) = \frac{s^2 - \omega^2}{(s^2 + \omega^2)^2} \quad \text{and} \quad \mathcal{L}[t \sin(\omega t)](s) = \frac{2\omega s}{(s^2 + \omega^2)^2}.$$

We would like to bring this expression to the form where we can recognize the transforms by inspection. One trick that works is to write

$$\frac{7}{8} \frac{1}{s^2 + 16} = \frac{1}{s^2 + 16} - \frac{1}{8} \frac{1}{s^2 + 16} = \frac{1}{s^2 + 16} - \frac{1}{8} \frac{s^2 + 16}{(s^2 + 16)^2}.$$

Then

$$-\frac{1}{8} \frac{s^2 + 16}{(s^2 + 16)^2} + \frac{4}{(s^2 + 16)^2} = -\frac{1}{8} \frac{s^2 - 16}{(s^2 + 16)^2} \quad (!).$$

So that

$$sL[y](s) = -\frac{1}{128} \frac{1}{s} + \frac{1}{16} \frac{2}{s^3} + \frac{s}{s^2 + 16} + \frac{1}{s^2 + 16} - \frac{1}{8} \frac{s^2 - 16}{(s^2 + 16)^2}$$

and

$$y(t) = -\frac{1}{128} + \frac{1}{16} t^2 + \cos(4t) + \frac{1}{4} \sin(4t) - \frac{1}{8} t \cos(4t),$$

in agreement with the solution found in Problem Set 06.

2. i) Show that $\int_0^\infty f(t)e^{-st} dt$ converges for $s = s_0 - \sigma$ if and only if $\int_0^\infty (e^{\sigma t} f(t)) e^{-st} dt$ converges for $s = s_0$.

Hence, show that if the domain of $\mathcal{L}[f]$ is all $s > a$, then the domain of $\mathcal{L}[e^{\sigma t} f]$ is all $s > a + \sigma$, and we have

$$\mathcal{L}[e^{\sigma t} f](s) = \mathcal{L}[f](s - \sigma) \quad \text{for all } s > a + \sigma.$$

- ii) Taking the four transforms

$$\mathcal{L}[\cos(\omega t)](s) = \frac{s}{s^2 + \omega^2}, \quad s > 0, \quad \mathcal{L}[\sin(\omega t)](s) = \frac{\omega}{s^2 + \omega^2}, \quad s > 0,$$

$$\mathcal{L}[t \cos(\omega t)](s) = \frac{s^2 - \omega^2}{(s^2 + \omega^2)^2}, \quad s > 0 \quad \text{and} \quad \mathcal{L}[t \sin(\omega t)](s) = \frac{2\omega s}{(s^2 + \omega^2)^2}, \quad s > 0$$

as known, find

$$\mathcal{L}[e^{\sigma t} \cos(\omega t)], \quad \mathcal{L}[te^{\sigma t} \cos(\omega t)], \quad \mathcal{L}[e^{\sigma t} \sin(\omega t)] \quad \text{and} \quad \mathcal{L}[te^{\sigma t} \sin(\omega t)].$$

Solution. i) We have

$$\int_0^\infty (e^{\sigma t} f(t)) e^{-st} dt = \int_0^\infty f(t) e^{-(s-\sigma)t} dt.$$

Therefore, $\int_0^\infty f(t) e^{-(s_0-\sigma)t} dt$ converges if and only if $\int_0^\infty (e^{\sigma t} f(t)) e^{-s_0 t} dt$ converges. They are the same integral!

Now, observe that this implies that $\int_0^\infty f(t) e^{-st} dt$ converges for $s = s_0$ if and only if $\int_0^\infty (e^{\sigma t} f(t)) e^{-st} dt$ converges for $s = s_0 + \sigma$.

Suppose that the domain of $\mathcal{L}[f]$ is all $s > a$, for some a (the other possibilities for the domain — $s \geq a$ and the empty set, can be handled similarly). This means that $\int_0^\infty f(t) e^{-st} dt$ converges if and only if $s > a$, by definition of the domain of $\mathcal{L}[f]$. By the observation of the previous paragraph, it follows that $\int_0^\infty (e^{\sigma t} f(t)) e^{-st} dt$ converges if and only if $s > a + \sigma$. Therefore, the domain of $\mathcal{L}[e^{\sigma t} f]$ is all $s > a + \sigma$.

We have, using the definition of Laplace transform,

$$\begin{aligned} \mathcal{L}[e^{\sigma t} f](s) &= \int_0^\infty (e^{\sigma t} f(t)) e^{-st} dt \\ &= \int_0^\infty f(t) e^{-(s-\sigma)t} dt \\ &= \mathcal{L}[f](s - \sigma) \quad \text{for all } s > a + \sigma \end{aligned}$$

ii) Applying the first part, we have

$$\begin{aligned}\mathcal{L}[e^{\sigma t} \cos(\omega t)](s) &= \mathcal{L}[\cos(\omega t)](s - \sigma) = \frac{(s - \sigma)}{(s - \sigma)^2 + \omega^2}, \quad s > \sigma; \\ \mathcal{L}[t e^{\sigma t} \cos(\omega t)](s) &= \mathcal{L}[t \cos(\omega t)](s - \sigma) = \frac{(s - \sigma)^2 - \omega^2}{((s - \sigma)^2 + \omega^2)^2}, \quad s > \sigma; \\ \mathcal{L}[e^{\sigma t} \sin(\omega t)](s) &= \mathcal{L}[\sin(\omega t)](s - \sigma) = \frac{\omega}{(s - \sigma)^2 + \omega^2}, \quad s > \sigma; \\ \mathcal{L}[t e^{\sigma t} \sin(\omega t)](s) &= \mathcal{L}[t \sin(\omega t)](s - \sigma) = \frac{2\omega(s - \sigma)}{((s - \sigma)^2 + \omega^2)^2}, \quad s > \sigma.\end{aligned}$$

3. As a reminder, earlier in the term we defined the functions

$$\cosh(\omega t) = \frac{e^{\omega t} + e^{-\omega t}}{2} \quad \text{and} \quad \sinh(\omega t) = \frac{e^{\omega t} - e^{-\omega t}}{2}, \quad t \in \mathbb{R}.$$

Find expressions for $\mathcal{L}[\cosh(\omega t)]$ and $\mathcal{L}[\sinh(\omega t)]$ in the following two ways:

i) Take as known the transform

$$\mathcal{L}[e^{\sigma t}](s) = \frac{1}{s - \sigma}, \quad s > 0,$$

and use linearity of \mathcal{L} .

ii) Check that

$$\cosh(0) = 1, \quad \left. \frac{d}{dt} \cosh(\omega t) \right|_{t=0} = 0,$$

and

$$\sinh(0) = 0, \quad \left. \frac{d}{dt} \sinh(\omega t) \right|_{t=0} = \omega.$$

Then, find a linear homogeneous differential equation with constant coefficients that has \cosh and \sinh as solutions, apply \mathcal{L} to both sides of the differential equation, and use the initial conditions found above.

(Although you do not have to show this, the domain of both $\mathcal{L}[\cosh(\omega t)]$ and $\mathcal{L}[\sinh(\omega t)]$ is equal to $s > |\omega|$, as may be tempting to guess from the domains of $e^{\omega t}$ and $e^{-\omega t}$.)

Optional Problem. Compute $\mathcal{L}[\cosh(\omega t)]$ and $\mathcal{L}[\sinh(\omega t)]$ from the definition, and verify the claim just made about their domains.

Solution. i) By linearity of the Laplace transform, we have

$$\begin{aligned}\mathcal{L}[\cosh(\omega t)](s) &= \frac{1}{2} \mathcal{L}[e^{\omega t}](s) + \frac{1}{2} \mathcal{L}[e^{-\omega t}](s) \\ &= \frac{1}{2} \frac{1}{s - \omega} + \frac{1}{2} \frac{1}{s + \omega} \\ &= \frac{1}{2} \frac{(s + \omega) + (s - \omega)}{s^2 - \omega^2} \\ &= \frac{s}{s^2 - \omega^2},\end{aligned}$$

for all $s > \max(\omega, -\omega)$ (since the domains of $\mathcal{L}[e^{\omega t}]$ and $\mathcal{L}[e^{-\omega t}]$ are $s > \omega$ and $s > -\omega$, respectively), and

$$\begin{aligned}\mathcal{L}[\sinh(\omega t)](s) &= \frac{1}{2}\mathcal{L}[e^{\omega t}](s) - \frac{1}{2}\mathcal{L}[e^{-\omega t}](s) \\ &= \frac{1}{2} \frac{1}{s - \omega} - \frac{1}{2} \frac{1}{s + \omega} \\ &= \frac{1}{2} \frac{(s + \omega) - (s - \omega)}{s^2 - \omega^2} \\ &= \frac{\omega}{s^2 - \omega^2},\end{aligned}$$

for all $s > \max(\omega, -\omega)$.

Remarks. The domains of $\mathcal{L}[\cosh(\omega t)]$ and $\mathcal{L}[\sinh(\omega t)]$ could be larger than the regions where we can apply the linearity properties of \mathcal{L} , but in this example it turns out that they are not.

It is worth noticing how similar these expressions are to the Laplace transforms of \cos and \sin .

- ii) Since $\cosh(\omega t)$ and $\sinh(\omega t)$ are linear combinations of $e^{\omega t}$ and $e^{-\omega t}$, they are in fact quasipolynomials! The problem of finding an equation for \cosh and \sinh is equivalent to finding an annihilator of \cosh and \sinh , and we have previously (in Problem Set 06) developed some methods on how to find annihilators of linear combinations of functions.

The operator $\left(\frac{d}{dt} - \omega\right)$ is an annihilator of $e^{\omega t}$, and $\left(\frac{d}{dt} + \omega\right)$ is an annihilator of $e^{-\omega t}$. Therefore, the operator product

$$\left(\frac{d}{dt} - \omega\right)\left(\frac{d}{dt} + \omega\right) = \frac{d^2}{dt^2} - \omega^2$$

is an annihilator of any linear combination of $e^{\omega t}$ and $e^{-\omega t}$. In particular, it is an annihilator of both $\cosh(\omega t)$ and $\sinh(\omega t)$. Therefore, $\cosh(\omega t)$ and $\sinh(\omega t)$ are solutions of the differential equation

$$\frac{d^2 y}{dt^2} - \omega^2 y = 0. \tag{1}$$

Applying the Laplace transform to both sides of this equation, we get

$$\mathcal{L}\left[\frac{d^2 y}{dt^2}\right](s) - \omega^2 \mathcal{L}[y](s) = 0.$$

Therefore,

$$s^2 \mathcal{L}[y](s) - sy(0) - y'(0) - \omega^2 \mathcal{L}[y](s) = 0,$$

so that

$$(s^2 - \omega^2) \mathcal{L}[y](s) = sy(0) + y'(0).$$

Finally,

$$\mathcal{L}[y](s) = \frac{sy(0) + y'(0)}{s^2 - \omega^2}, \tag{2}$$

for any solution y of (1).

Computing the derivatives of $\cosh(\omega t)$ and $\sinh(\omega t)$, we have

$$(\cosh(\omega t))' = \left(\frac{e^{\omega t} + e^{-\omega t}}{2} \right)' = \frac{\omega e^{\omega t} - \omega e^{-\omega t}}{2} = \omega \left(\frac{e^{\omega t} - e^{-\omega t}}{2} \right) = \omega \sinh(\omega t),$$

and

$$(\sinh(\omega t))' = \left(\frac{e^{\omega t} - e^{-\omega t}}{2} \right)' = \frac{\omega e^{\omega t} + \omega e^{-\omega t}}{2} = \omega \cosh(\omega t).$$

Moreover, $\cosh(0) = \frac{e^0 + e^0}{2} = 1$ and $\sinh(0) = \frac{e^0 - e^0}{2} = 0$, so that

$$\cosh(0) = 1, \quad \left. \frac{d}{dt} \cosh(\omega t) \right|_{t=0} = \omega \sinh(0) = 0,$$

and

$$\sinh(0) = 0, \quad \left. \frac{d}{dt} \sinh(\omega t) \right|_{t=0} = \omega \cosh(0) = \omega.$$

Finally, using result (2) with these initial conditions, we see that the Laplace transforms of $\cosh(\omega t)$ and $\sinh(\omega t)$ are

$$\mathcal{L}[\cosh(\omega t)](s) = \frac{s \cdot 1 + 0}{s^2 - \omega^2} = \frac{s}{s^2 - \omega^2}$$

and

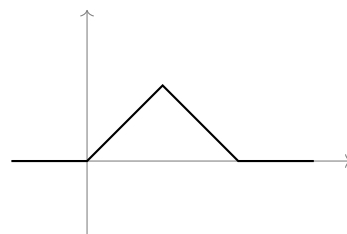
$$\mathcal{L}[\sinh(\omega t)](s) = \frac{s \cdot 0 + \omega}{s^2 - \omega^2} = \frac{\omega}{s^2 - \omega^2}.$$

4. Let f and g denote the following two functions.



$$f(t) = \begin{cases} 1 & 0 \leq t \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

and



$$g(t) = \begin{cases} t & 0 \leq t \leq 1 \\ 2 - t & 1 \leq t \leq 2 \\ 0 & \text{otherwise} \end{cases}$$

i) Show that the convolution $f * f$ of f with itself is equal to g , in the following two ways.

First, compute $f * f$ using the definition of convolution

$$(f * f)(t) = \int_{-\infty}^{\infty} f(u)f(t-u) du$$

and check that the result is equal to g .

Second, write both f and g as an expression involving step functions, and apply the property $\mathcal{L}[f * f] = \mathcal{L}[f]\mathcal{L}[f]$ of the Laplace transform.

ii) Compute the convolution $(2f) * g$ of $2f$ with g in the same two ways as part i).

Optional Problem. Investigate the motion of a simple harmonic oscillator starting from rest

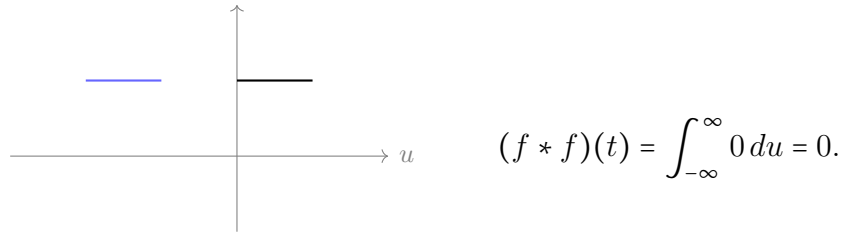
$$\frac{d^2y}{dt^2} + y = F(t), \quad y(0) = 0, \quad \frac{dy}{dt}(0) = 0,$$

subject to forcing functions $f(t)$, $g(t)$ and $((2f) * g)(t)$.

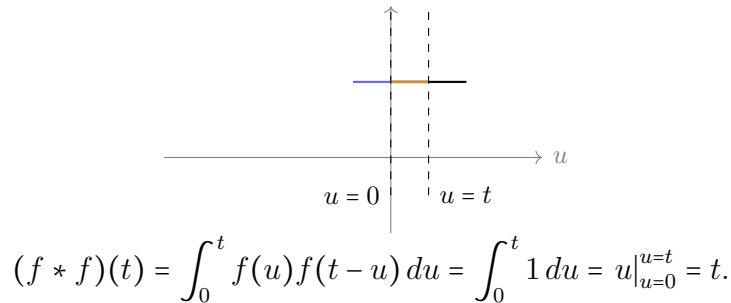
Solution. i) The computation breaks up into a number of cases based on the intersection of the graph of $f(u)$ with the graph of $f(t-u)$. We can think of the latter as the graph of f , but reflected about the y -axis, and translated by t to the right (or, more generally, translated by t along the positive u -direction).

We adopt the convention that the fixed graph of $f(u)$ is in black, and the sliding graph of $f(t-u)$ is in blue. When the two graphs overlap along a line segment, we shall denote the overlap in orange. Moreover, we omit the graphs of both where they are equal to zero.

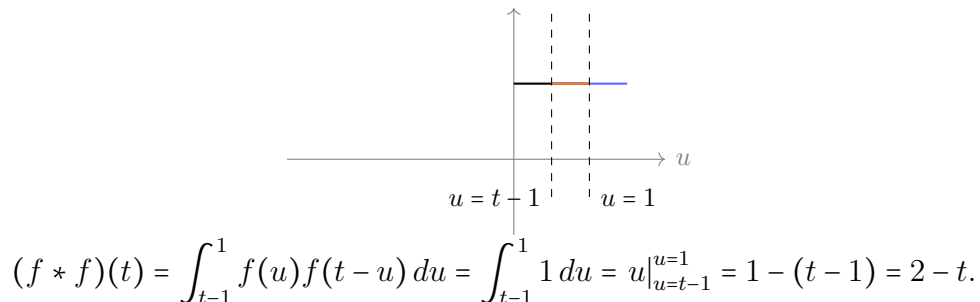
Case $t < 0$: The regions where $f(u)$ and $f(t-u)$ are nonzero do not overlap. Therefore, their product $f(u)f(t-u)$ is equal to 0 for all u , and



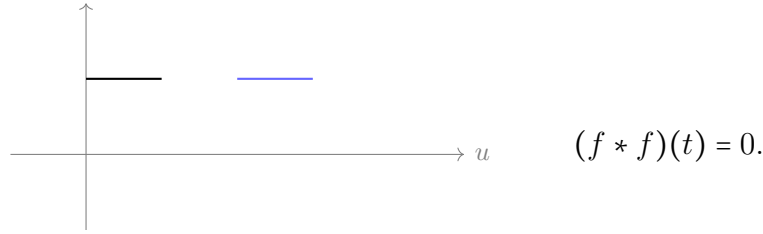
Case $0 \leq t < 1$: The tip of $f(t-u)$ crosses over into the region where $f(u)$ is nonzero.



Case $1 \leq t < 2$: The tip of $f(t-u)$ passes the region where $f(u)$ is nonzero, but the tail of $f(t-u)$ still overlaps the region.



Case $t \geq 2$: The graph of $f(t-u)$ completely passes the region where $f(u)$ is nonzero, so the product $f(u)f(t-u)$ is again zero.



In summary,

$$(f * f)(t) = \begin{cases} t & 0 \leq t \leq 1 \\ 2 - t & 1 \leq t \leq 2 \\ 0 & \text{otherwise} \end{cases},$$

so that $(f * f)(t) = g(t)$ for all $t \in \mathbb{R}$.

Writing f using unit step functions, we have

$$f(t) = u_0(t) - u_1(t) \quad \text{for all } t.$$

Therefore,

$$\mathcal{L}[f](s) = \frac{e^{-0s}}{s} - \frac{e^{-1s}}{s} = \frac{1}{s} - \frac{e^{-s}}{s}.$$

By the convolution theorem,

$$\mathcal{L}[f * f](s) = \mathcal{L}[f](s) \mathcal{L}[f](s) = \left(\frac{1}{s} - \frac{e^{-s}}{s} \right)^2 = \frac{1}{s^2} - \frac{2}{s^2} e^{-s} + \frac{1}{s^2} e^{-2s}.$$

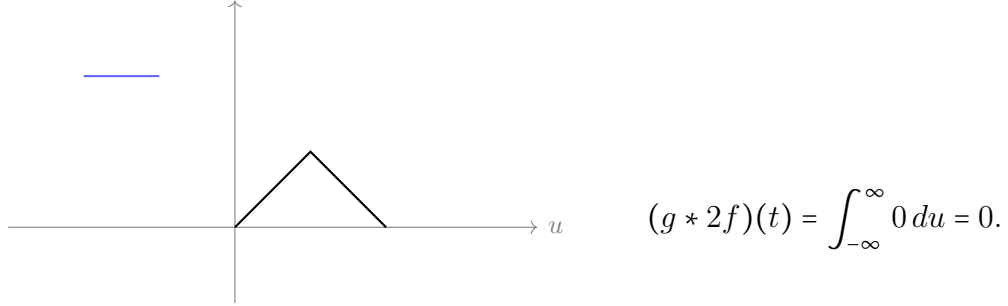
We can find the inverse Laplace transform using the property that if $Y(s) = \mathcal{L}[y](s)$, then $\mathcal{L}^{-1}[e^{-as}Y] = u_a(t)y(t-a)$. Remembering that $\mathcal{L}^{-1}[\frac{1}{s^2}] = t$, we have

$$\begin{aligned} (f * f)(t) &= u_0(t)t - 2u_1(t)(t-1) + u_2(t)(t-2) \\ &= \begin{cases} 0 & t < 0 \\ t & 0 \leq t < 1 \\ t - 2(t-1) = 2 - t & 1 < t \leq 2 \\ (2-t) + (t-2) = 0 & t > 2 \end{cases} \end{aligned}$$

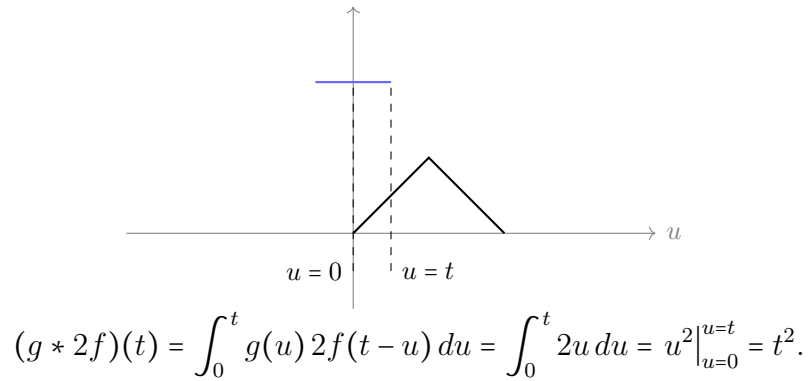
which once again recovers $g(t)$ for all $t \in \mathbb{R}$.

- ii) By a property proved in class, $(2f * g) = (g * 2f)$. We compute the second instead, because it is somewhat simpler to imagine sliding a horizontal line segment. We proceed as in part i), with the same conventions.

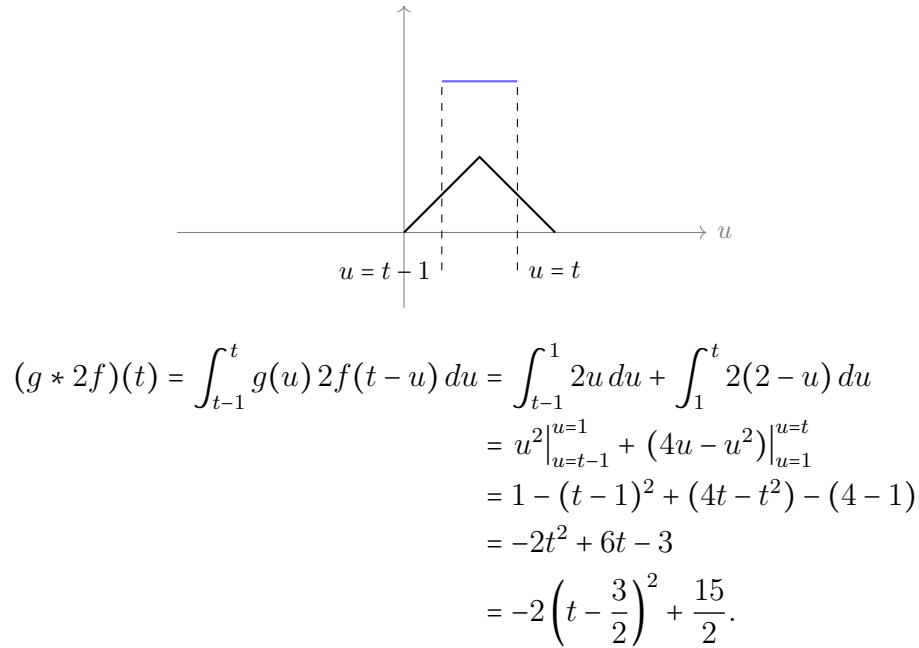
Case $t < 0$: The regions where $g(u)$ and $2f(t-u)$ are nonzero do not overlap. Therefore, their product $g(u)2f(t-u)$ is equal to 0 for all u , and



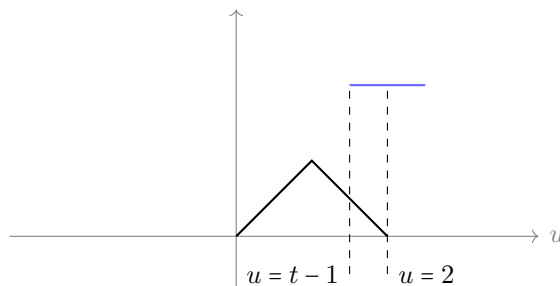
Case $0 \leq t < 1$: The tip of the segment $2f(t-u)$ overlaps the region where $g(u)$ is nonzero.



Case $1 \leq t < 2$: The entire segment $2f(t-u)$ overlaps the region where $g(u)$ is nonzero.

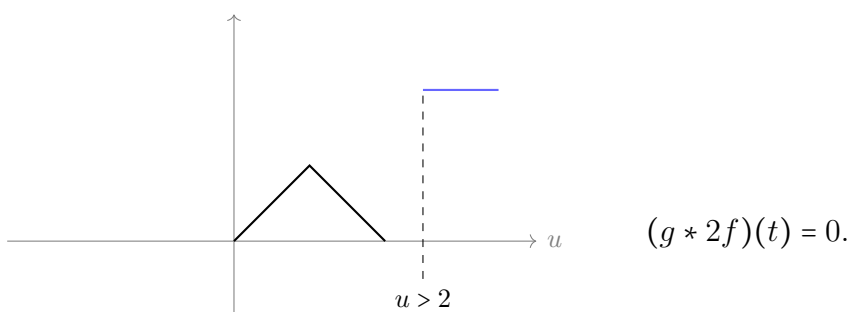


Case $2 \leq t < 3$: The tail of the segment $2f(t-u)$ overlaps the region where $g(u)$ is nonzero.



$$(g * 2f)(t) = \int_{t-1}^2 g(u) 2f(t-u) du = \int_{t-1}^2 2(2-u) du = (4u - u^2) \Big|_{u=t-1}^{u=2} = t^2 - 6t + 9 = (t-3)^2.$$

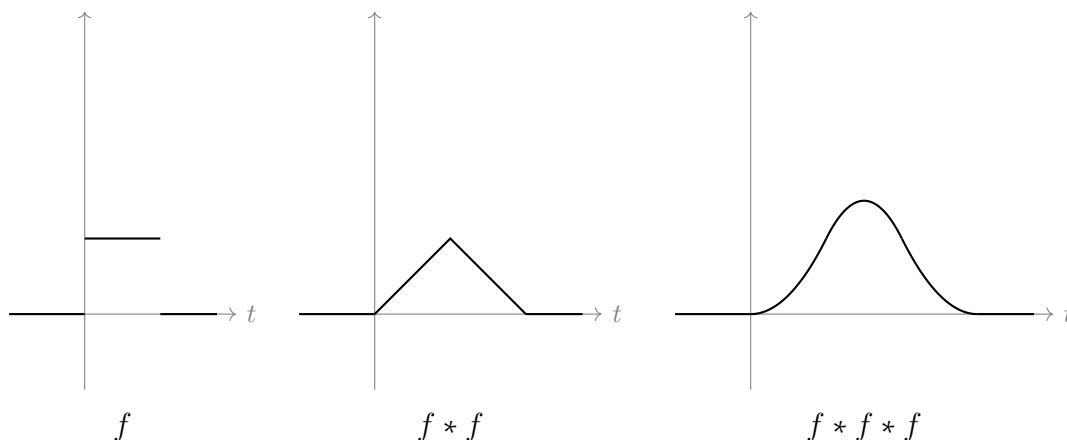
Case $t \geq 3$: The tail of the segment $2f(t-u)$ passes the region where $g(u)$ is nonzero.



In summary,

$$(g * 2f)(t) = \begin{cases} t^2 & 0 \leq t < 1 \\ -2t^2 + 6t - 3 & 1 \leq t < 2 \\ t^2 - 6t + 9 & 2 \leq t < 3 \\ 0 & \text{otherwise} \end{cases} = \begin{cases} t^2 & 0 \leq t < 1 \\ -2\left(t - \frac{3}{2}\right)^2 + \frac{15}{2} & 1 \leq t < 2 \\ (t-3)^2 & 2 \leq t < 3 \\ 0 & \text{otherwise} \end{cases}.$$

The graph of $(g * 2f)$ is a nice union of three parabolas. The function $(g * 2f)$, which we can think of as $f * f * f$ (up to multiplying by 2), is now differentiable (whereas f was discontinuous, and $f * f$ was merely continuous).



Finally, we know from the previous part that

$$\mathcal{L}[g](s) = \frac{1}{s^2} (1 - 2e^{-s} + e^{-2s}).$$

By the convolution theorem,

$$\begin{aligned} \mathcal{L}[g * 2f](s) &= \mathcal{L}[g](s)\mathcal{L}[2f](s) = \frac{1}{s^2} (1 - 2e^{-s} + e^{-2s}) 2 \left(\frac{1}{s} - \frac{e^{-s}}{s} \right) \\ &= \frac{2}{s^3} (1 - 3e^{-s} + 3e^{-2s} - e^{-3s}). \end{aligned}$$

By the translation theorem (recalling that $\mathcal{L}[t^2](s) = 2/s^3$), we conclude that

$$(g * 2f)(t) = u_0(t)t^2 - 3u_1(t)(t-1)^2 + 3u_2(t)(t-2)^2 - u_3(t)(t-3)^2.$$

Writing out the pieces,

$$(g * 2f)(t) = \begin{cases} 0 & t < 0 \\ t^2 & 0 \leq t < 1 \\ t^2 - 3(t-1)^2 = -2t^2 + 6t - 3 & 1 \leq t < 2 \\ (-2t^2 + 6t - 3) + 3(t-2)^2 = t^2 - 6t + 9 & 2 \leq t < 3 \\ (t^2 - 6t + 9) - (t-3)^2 = 0 & t \geq 3 \end{cases}.$$

This is the same answer as before!