

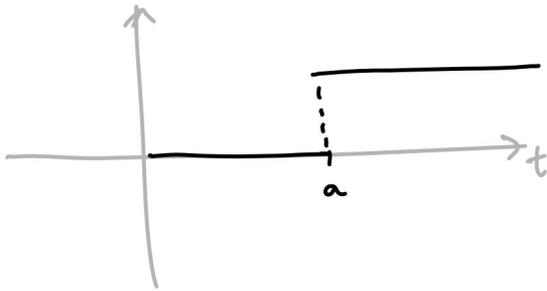
Mthe 237
Lecture 26
Nov. 08, 2017

Topic : Examples of working with
piecewise-defined forcing functions

§ Translations and the Laplace transform

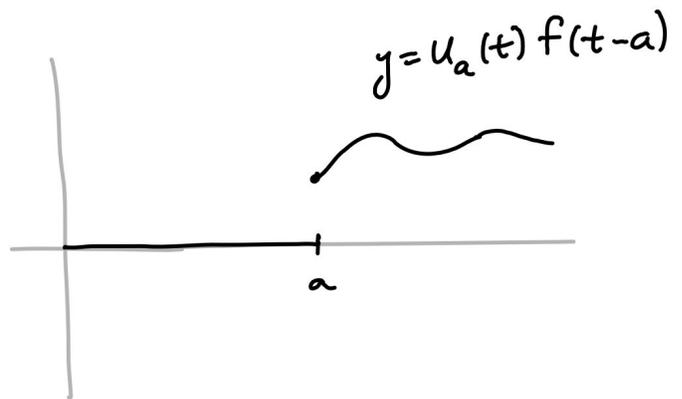
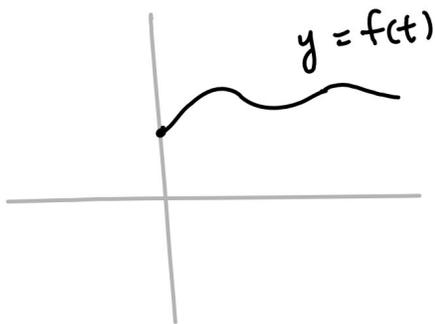
Reminders from last time:

$$u_a(t) = \begin{cases} 1, & t \geq a \\ 0, & 0 \leq t < a \end{cases}$$



is the unit step function
with jump at $t = a$

We denote by $u_a(t) f(t-a)$ the translate
of the function f by a in the positive t
direction.



Prop. Suppose $\mathcal{L}[f](s_0)$ converges. Then for any $a \geq 0$, $\mathcal{L}[u_a(t)f(t-a)](s_0)$ also converges and

$$\mathcal{L}[u_a(t)f(t-a)](s_0) = e^{-as} \mathcal{L}[f](s_0).$$

Proof: $\mathcal{L}[u_a(t)f(t-a)](s)$

$$= \int_0^{\infty} u_a(t) f(t-a) e^{-st} dt$$

$$= \int_a^{\infty} f(t-a) e^{-st} dt.$$

Use the change of variable $u = t - a$
 $du = dt$

$$= \int_0^{\infty} f(u) e^{-s(u+a)} du$$

$$= e^{-as} \int_0^{\infty} f(u) e^{-su} du.$$

$$= e^{-as} \mathcal{L}[f](s).$$

Corollary: If $f = \mathcal{L}^{-1}[F]$, then

$$u_a(t) f(t-a) = \mathcal{L}^{-1}[e^{-as} F].$$

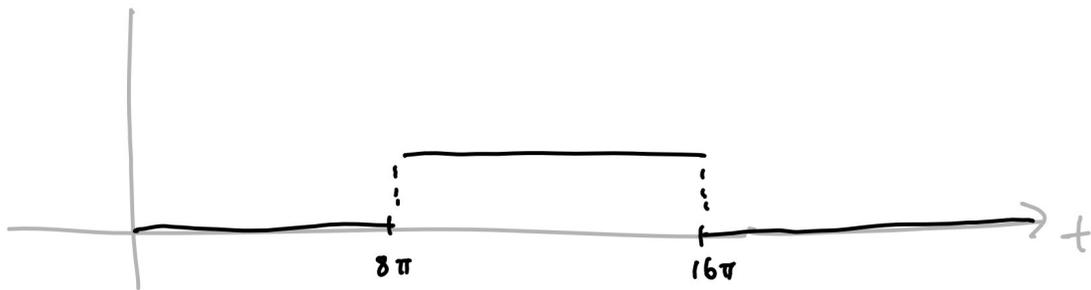
This proposition lets us work cleanly with forcing functions that are defined piecewise. For the rest of today, we work out two examples for the differential equation

$$\frac{d^2 y}{dt^2} + \frac{1}{2} \frac{dy}{dt} + \frac{5}{16} y = F(t), \quad \begin{aligned} y(0) &= 0, \\ \frac{dy}{dt}(0) &= 0, \end{aligned}$$

which can be thought of as an underdamped harmonic oscillator starting from rest.

§ Examples

1. $F(t) = u_{8\pi}(t) - u_{16\pi}(t)$



Applying the Laplace transform to both sides of our differential equation, we get

$$s^2 \mathcal{L}[y](s) + \frac{s}{2} \mathcal{L}[y](s) + \frac{5}{16} \mathcal{L}[y](s) = \frac{e^{-8\pi s}}{s} - \frac{e^{-16\pi s}}{s}$$

$$\left(s^2 + \frac{s}{2} + \frac{5}{16}\right) \mathcal{L}[y](s) = \frac{e^{-8\pi s}}{s} - \frac{e^{-16\pi s}}{s}$$

$$\mathcal{L}[y](s) = \left(\frac{1}{\left(s^2 + \frac{s}{2} + \frac{5}{16}\right)s} \right) (e^{-8\pi s} - e^{-16\pi s})$$

$$\text{Let } H(s) = \left(\frac{1}{\left(s^2 + \frac{s}{2} + \frac{5}{16}\right)s} \right)$$

$$\text{and } h(t) = \mathcal{L}^{-1}[H].$$

By the Corollary above, the solution is then

$$y(t) = u_{8\pi}(t) h(t - 8\pi) - u_{16\pi}(t) h(t - 16\pi).$$

So it is enough to find h .

First, look for a partial fraction decomposition:

$$\frac{1}{\left(s^2 + \frac{s}{2} + \frac{5}{16}\right)s} = \frac{As + B}{s^2 + \frac{s}{2} + \frac{5}{16}} + \frac{C}{s}$$

$$= \frac{As^2 + Bs + C\left(s^2 + \frac{s}{2} + \frac{5}{16}\right)}{\left(s^2 + \frac{s}{2} + \frac{5}{16}\right)s}$$

$$\left. \begin{array}{l} A + C = 0 \\ B + \frac{C}{2} = 0 \\ \frac{5}{16}C = 1 \end{array} \right\} \Rightarrow A = -\frac{16}{5}, \quad B = -\frac{8}{5}, \quad C = \frac{16}{5}$$

$$H(s) = \frac{8}{5} \left(\frac{-2s-1}{s^2 + \frac{s}{2} + \frac{5}{16}} + \frac{2}{s} \right)$$

Now recall that

$$\mathcal{L}[e^{\sigma t} \cos(\omega t)](s) = \frac{(s-\sigma)}{(s-\sigma)^2 + \omega^2},$$

$$\mathcal{L}[e^{\sigma t} \sin(\omega t)](s) = \frac{\omega}{(s-\sigma)^2 + \omega^2}.$$

$\frac{2s+1}{s^2 + \frac{s}{2} + \frac{5}{16}}$ can be written as a linear combination of these two transforms.

Completing the square,

$$\begin{aligned} s^2 + \frac{s}{2} + \frac{5}{16} &= \left(s + \frac{1}{4}\right)^2 - \frac{1}{16} + \frac{5}{16} \\ &= \left(s + \frac{1}{4}\right)^2 + \frac{1}{4}. \end{aligned}$$

$$\text{So } \sigma = -\frac{1}{4}, \quad \omega = \frac{1}{2}.$$

$$2s+1 = 2\left(s + \frac{1}{4}\right) + \frac{1}{2}, \quad \text{so}$$

$$\frac{2s+1}{s^2 + \frac{s}{2} + \frac{5}{16}} = 2 \frac{s + \frac{1}{4}}{\left(s + \frac{1}{4}\right)^2 + \frac{1}{4}} + \frac{\frac{1}{2}}{\left(s + \frac{1}{4}\right)^2 + \frac{1}{4}}$$

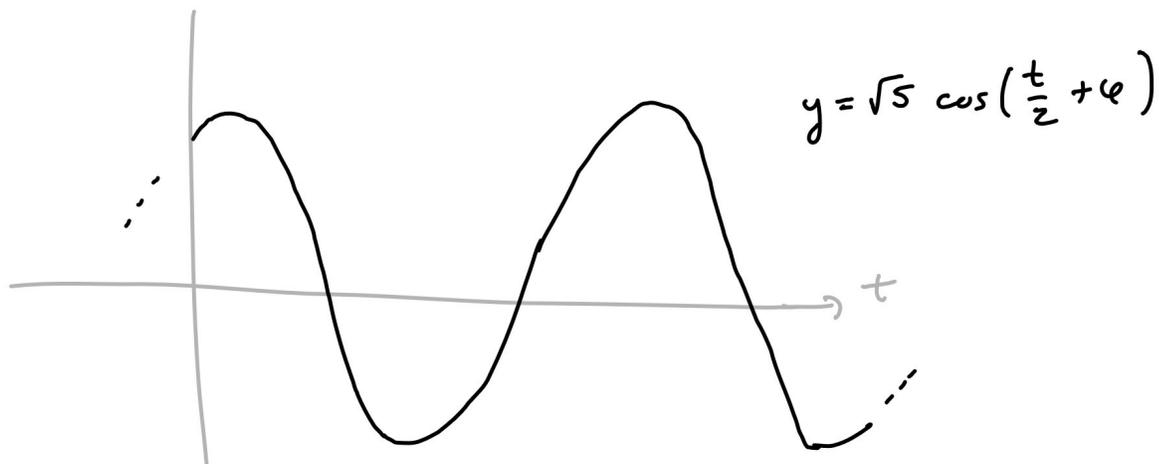
$$\mathcal{L}^{-1}\left[\frac{2s+1}{s^2 + \frac{s}{2} + \frac{5}{16}}\right] = 2e^{-t/4} \cos\left(\frac{t}{2}\right) + e^{-t/4} \sin\left(\frac{t}{2}\right).$$

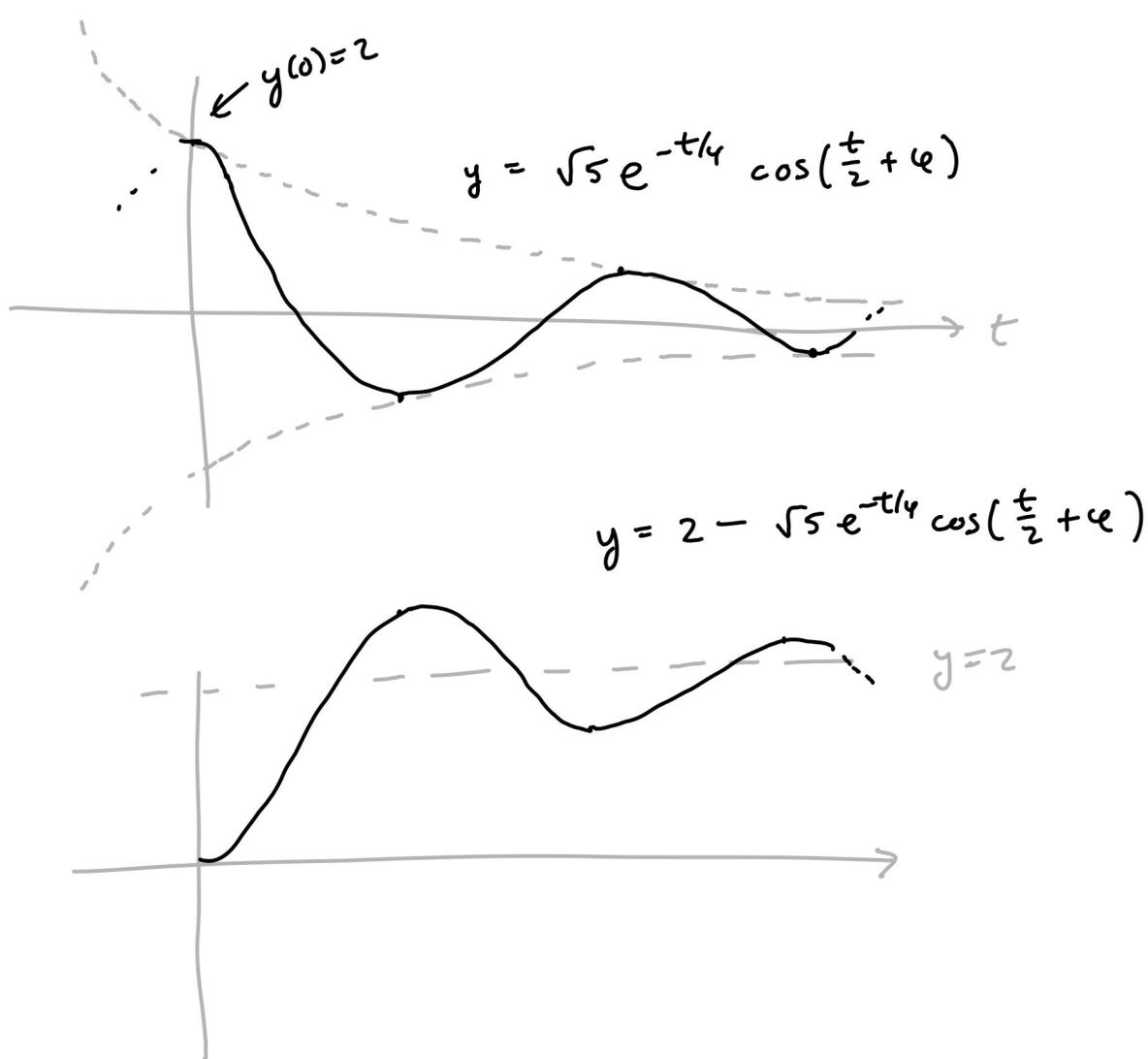
So that finally

$$h(t) = \mathcal{L}^{-1}[H] = \frac{8}{5} \left(2 - 2e^{-t/4} \cos\left(\frac{t}{2}\right) - e^{-t/4} \sin\left(\frac{t}{2}\right) \right)$$

To understand the graph of h , it is helpful to switch the last two terms to phase-amplitude form

$$\left[\begin{aligned} a_1 \cos(\omega t) + a_2 \sin(\omega t) &= A \cos(\omega t + \varphi), \\ \text{where} \\ A &= \sqrt{a_1^2 + a_2^2} \\ \tan \varphi &= -\frac{a_2}{a_1} \\ \text{So } e^{-t/4} \left(2 \cos\left(\frac{t}{2}\right) + \sin\left(\frac{t}{2}\right) \right) \\ &= e^{-t/4} \sqrt{5} \cos\left(\frac{t}{2} + \varphi\right), \quad \text{where} \\ &\quad \varphi = \arctan\left(-\frac{1}{2}\right) \\ &\quad \approx -26^\circ \end{aligned} \right]$$



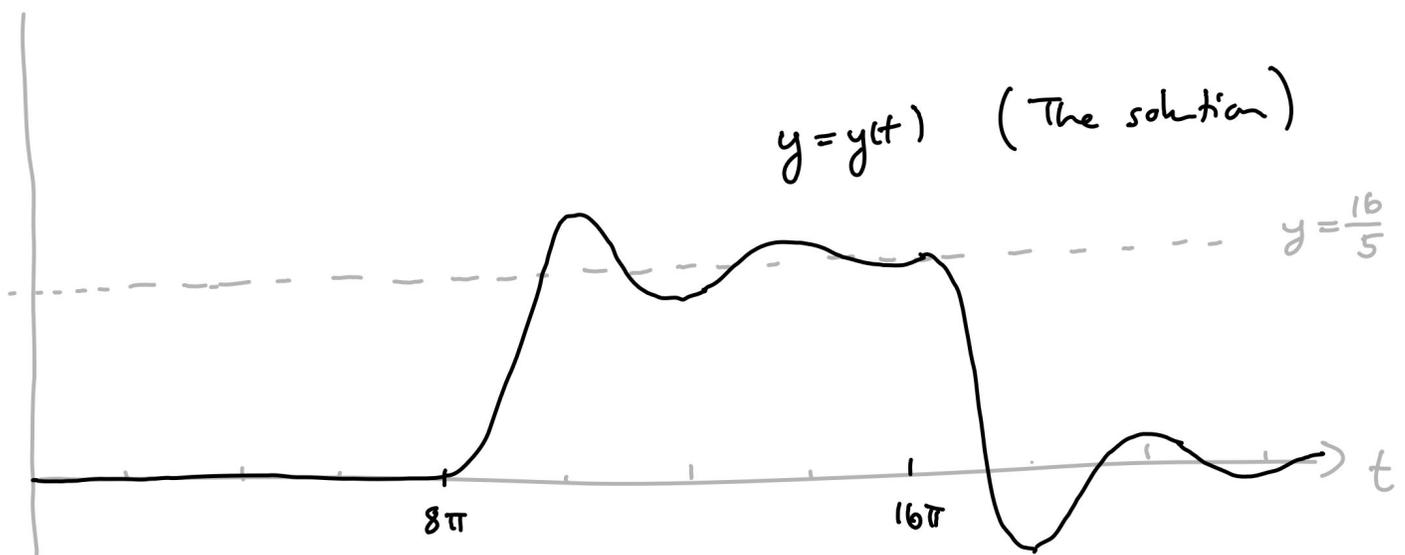


We can think of this graph (up to scaling by $\frac{8}{5}$) as the "system response" to a forcing term that is a unit step function.

The solution $y(t)$ is a superposition of two such responses, which we can sketch as follows:

$$y(t) = u_{8\pi}(t) h(t-8\pi) + u_{16\pi}(t) h(t-16\pi)$$

$$= \begin{cases} 0, & 0 \leq t < 8\pi \\ \frac{8}{5} \left(2 - \sqrt{5} e^{-\frac{(t-8\pi)}{4}} \cos\left(\frac{t-8\pi}{2} + \varphi\right) \right) \\ \quad = \frac{8}{5} \left(2 - \sqrt{5} e^{-(t-8\pi)/4} \cos\left(\frac{t}{2} + \varphi\right) \right), & 8\pi \leq t < 16\pi \\ \frac{8}{5} \left(2 - \sqrt{5} e^{-(t-8\pi)/4} \cos\left(\frac{t}{2} + \varphi\right) \right) \\ \quad - \frac{8}{5} \left(2 - \sqrt{5} e^{-(t-16\pi)/4} \cos\left(\frac{t-16\pi}{2} + \varphi\right) \right), & t > 16\pi \\ \quad = \frac{8}{5} \left(\sqrt{5} \left(e^{-(t-16\pi)/4} - e^{-(t-8\pi)/4} \right) \cos\left(\frac{t}{2} + \varphi\right) \right) \end{cases}$$

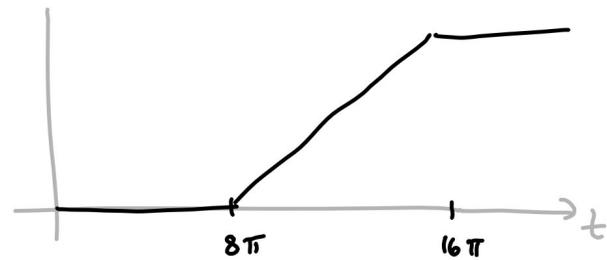


Fft):



2. Consider the same system with an input that ramps between two constant values:

$$F(t) = \begin{cases} 0, & 0 < t < 8\pi \\ t - 8\pi, & 8\pi \leq t < 16\pi \\ 8\pi, & t \geq 16\pi \end{cases}$$



$$F(t) = u_{8\pi}(t)(t - 8\pi) - u_{16\pi}(t)(t - 16\pi)$$

$$\mathcal{L}[F](s) = \frac{e^{-8\pi s}}{s^2} - \frac{e^{-16\pi s}}{s^2}$$

Proceeding similarly to the previous example, we have

$$\mathcal{L}[y](s) = \underbrace{\left(\frac{1}{(s^2 + \frac{s}{2} + \frac{s}{16})s^2} \right)}_{H(s)} (e^{-8\pi s} - e^{-16\pi s})$$

$$\text{Let } h(t) = \mathcal{L}^{-1}[H]$$

$$\text{Then } y(t) = u_{8\pi}(t)h(t - 8\pi) - u_{16\pi}(t)h(t - 16\pi).$$

We decompose $H(s)$ into partial fractions:

$$\frac{1}{(s^2 + \frac{s}{2} + \frac{5}{16})s^2} = \frac{As+B}{s^2 + \frac{s}{2} + \frac{5}{16}} + \frac{C}{s} + \frac{D}{s^2}$$

$$= \frac{As^3 + Bs^2 + C(s^2 + \frac{s}{2} + \frac{5}{16}s) + D(s^2 + \frac{s}{2} + \frac{5}{16})}{(s^2 + \frac{s}{2} + \frac{5}{16})s^2}$$

$$\left. \begin{aligned} A + C &= 0 \\ B + \frac{C}{2} + D &= 0 \\ \frac{5}{16}C + \frac{D}{2} &= 0 \\ \frac{5}{16}D &= 1 \end{aligned} \right\} \begin{aligned} D &= \frac{16}{5}, \quad C = -\frac{8}{5} \cdot \frac{16}{5} \\ A &= \frac{8}{5} \cdot \frac{16}{5} \\ B &= \frac{16}{5} \left(\frac{4}{5} - 1 \right) = -\frac{16}{25} \end{aligned}$$

$$H(s) = \frac{16}{25} \left(\frac{8s-1}{s^2 + \frac{s}{2} + \frac{5}{16}} - \frac{8}{s} + \frac{5}{s^2} \right)$$

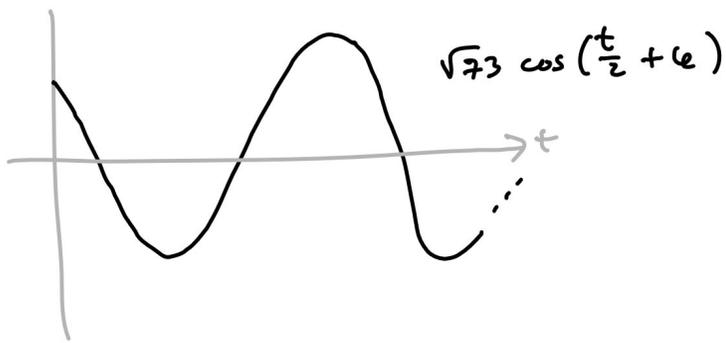
Now,

$$8s-1 = 8\left(s + \frac{1}{4}\right) - 3, \quad \text{so}$$

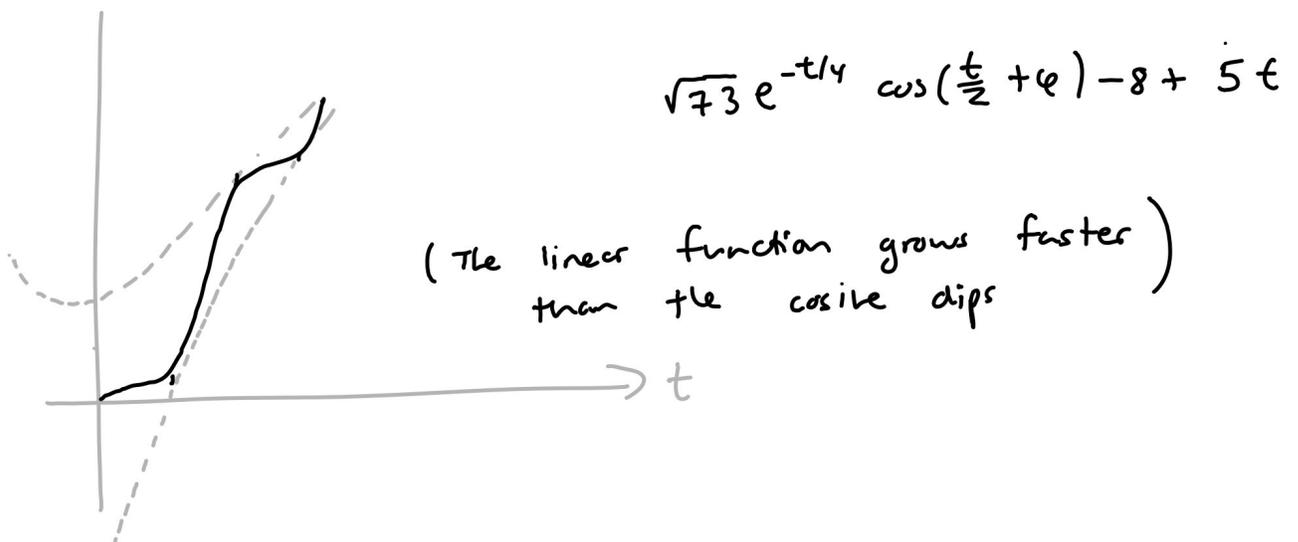
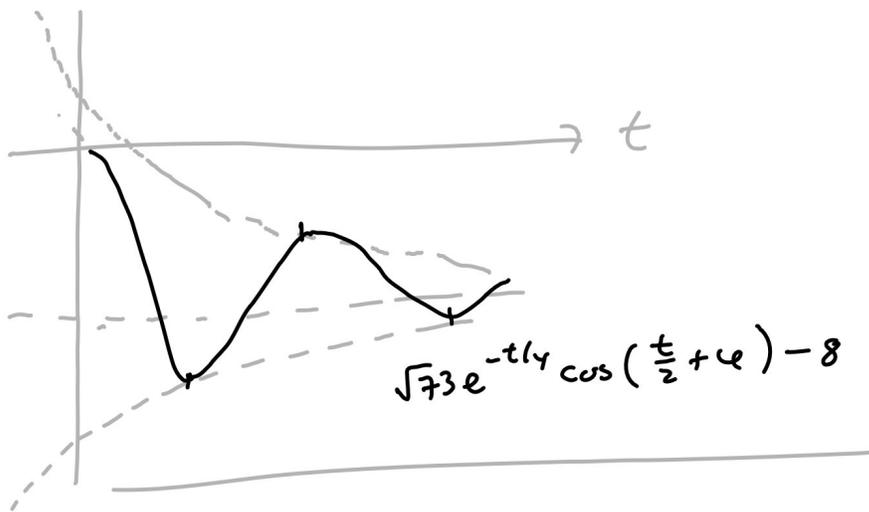
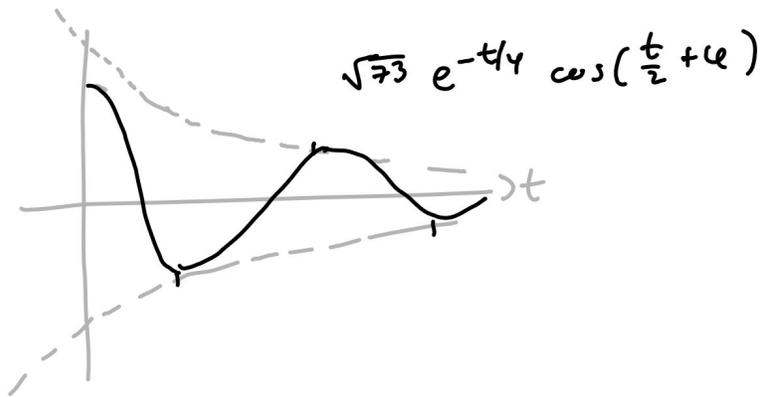
$$h(t) = \mathcal{L}^{-1}[H] = \frac{16}{25} \left(8e^{-t/4} \cos\left(\frac{t}{2}\right) - 3e^{t/4} \sin\left(\frac{t}{2}\right) - 8 + 5t \right)$$

$$= \frac{16}{25} \left(\sqrt{73} e^{-t/4} \cos\left(\frac{t}{2} + \varphi\right) - 8 + 5t \right)$$

$$\varphi = \arctan\left(\frac{3}{8}\right) \approx 21^\circ$$



1.)



(The linear function grows faster than the cosine dips)

$$y(t) = u_{8\pi}(t) h(t-8\pi) - u_{16\pi}(t) h(t-16\pi)$$

$$= 0 \quad \text{for} \quad 0 \leq t < 8\pi,$$

$$\frac{16}{25} \left(\sqrt{73} e^{-(t-8\pi)/4} \cos\left(\frac{t}{2} + \varphi\right) - 8 + 5(t-8\pi) \right), \quad 8\pi \leq t < 16\pi$$

$$\frac{16}{25} \left(\sqrt{73} \left(e^{-(t-8\pi)/4} - e^{-(t-16\pi)/4} \right) \cos\left(\frac{t}{2} + \varphi\right) + 40\pi \right), \quad t > 16\pi$$

