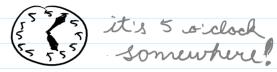
## L9: Approximating Work, Path-Independence

September 29, 2016 1:30 PM

Clockwise or Counterclockwise?

t -> (2 cos(t), sin(2t)), t & [0, 2T]





Terminology about curves: A parameterized path [a,b] -> 1R2 or 1R3 t → デ(t)

is said to be:

· Simple if it has no self-intersections 7(+)=7(5) = +=5 (Except if t= a and s=b

· Closed if r(a) = r(b)

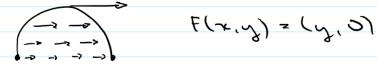
A curve in 12° or 123 is said to be:

- · Parametrizable if there exists a 1-1 parametrization of the curve,
- · Oriented if parametritable and a choice of orientation is made.



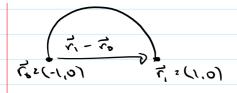
oriented briented both oriented, but different direction

Approximating work:

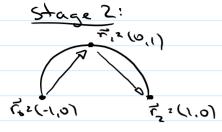


Let's write out a few stages of the limiting sum: いっとだけいか

Stage 1:



$$\vec{r}, -\vec{r}_0 = (1,0) - (-1,0)$$
 $\vec{r}(\vec{r}_0) = 0 \approx coork$ 
 $\vec{r}(\vec{r}_0) \cdot (\vec{r}_1 - \vec{r}_0) = 0 \approx coork$ 



1 = 1 + 0 = yow

\* Skip Stage 3

パーパーパー (1) 1 (1)

デ(で) 2 0 デ(デ) 2 (元,の) デ(で) 2 (1,の) ド(で) 2 (元,の)

work × 0+ (え) + (を) + (を)・(を) = 0 + と な な を - を = 2 を = 12 2 (・414) = 2 を = 12 2 (・414)

Define the work done by Falong Caste limit

But, peranetrizing C by  $t \mapsto \vec{r}(t)$ , and taking t: so that  $\vec{r}_{i} = \vec{r}(t)$ ,  $\vec{r}_{i+1} - \vec{r}_{i} \ge r(t_{i+1}) - \vec{r}(t)$ 

Path-Independence

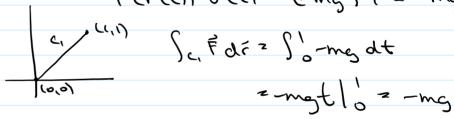
## Detin

A vector field is said to be conservative (or path independent) if the value of J. F.dr depends only on the endpoints of C (and their order)



If F is conservative, work done along all these curves is equal.

## Example 1



Cz: perabolic line segment

(' any parendrited path between (0,0) and (1,1)

the Fly z (x(y), y(y)) to [a,6]

3 (t) = (xit), y'(t))

F(r(t)). J(t) = -mgy'(t)

S=-mgy'(t) dt

=-mg (y(b) - y(a))

=-mg (1-0) =-mg.

## Goal:

Study recessary onch sufficient condutions for aveetor field to be conservative.